Héctor Barreiro Cabrera, Ph.D. in Computer Science

GITHUB hecbarcab PORTFOLIO hecbarcab.github.io EMAIL hecbarcab@gmail.com RESIDENCE Valencia, Spain

WORK EXPERIENCE

Jun 2022 -Today

Senior Scientist

SEDDI Inc, Madrid, Spain

SEDDI

- Implemented state-of-the-art methods to generate personalized avatars using statistical models, with a focus on seamless integration within a PyTorch-based machine learning
- Led the refactorization of the avatar generation pipeline to enhance maintainability and resilience to bugs, adhering rigorously to industry-leading quality standards and design best practices.
- Optimized critical data structures to enable vectorized evaluation of algorithms, resulting in dramatic reductions in execution times by up to two orders of magnitude.
- Modeled and implemented new functionalities within a real-time cloth simulation engine. This resulted in greater robustness and realism, allowing users to accurately predict drape.

May 2021 -Apr 2022

Research Engineer

Meta Reality Labs Research, Redmond, USA



- Developed robust techniques for simulating interactive soft-body objects, meticulously designed to leverage CPU vectorization instructions (SIMD) for superior performance.
- Overhauled the simulation framework to support both CPU and GPU-accelerated solvers through template metaprogramming, reducing code redundancy across multiple backends.

Aug. 2020 -Nov. 2020

Research Intern

Meta Reality Labs Research, Redmond, USA



Prototyped GPU-based acceleration strategies for high-fidelity finite element analysis, resulting in significant performance improvements over baseline CPU implementations.

Nov. 2015 -Apr. 2021

Student Researcher

Universidad Rey Juan Carlos, Móstoles, Spain



- Conducted research and development on a novel XPBD-based constraint model for simulating extremely viscous and viscoelastic fluids. This project was developed in collaboration with AnyVerse (formerly Next Limit), and integrated into the commercial CFD solver RealFlow.
- Explored haptic rendering methods for interacting with virtual fluids. Devised novel optimization strategies for driving ultrasonic haptic devices to replicate simulated pressure fields on users' hands. Implemented GPU-accelerated Eulerian fluid solvers for real-time simulation.
- Engaged in reading seminars to discuss the latest advancements in physics-based simulation within computer graphics, their foundational principles and avenues for further development.
- Collaborated closely with fellow lab members on the production of papers and demos, ensuring timely submissions to meet project deadlines.

Feb 2020 -

Research Intern

Mar. 2020

Ultraleap Ltd, Bristol, UK

Developed a model to describe the pressure exerted by single focal-point ultrasonic transducer arrays. Integrated this model into a soft-body simulation framework to estimate the deflection and propagation of mechanical waves within a skin phantom.

Dec. 2017 -Sept. 2018

Student Researcher

AnyVerse (formerly Next Limit), Madrid, Spain

Explored machine learning-based methods to infer the time evolution of fluid dynamic states. Funded by Spain's government under the *Doctorados Industriales* program (ref. DI-16-08640).

Oct. 2013 -Feb. 2015

Junior Programmer

IRTIC, Paterna, Spain



- Ported training simulator for cargo handling in port operations under Unity.
- Developed multiple Augmented Reality interactive marketing applications and demos using Unity and Vuforia.



EDUCATION

Sep. 2016 -Sep. 2021

Ph.D. in Computer Science

Higher School of Computer Engineering, Universidad Rey Juan Carlos, Spain

Supervised by Prof. Miguel A. Otaduy.



Curriculum Vitae Héctor Barreiro Cabrera

Sep. 2015 – Master's Degree in Computer Graphics, Videogames and VR

Higher School of Computer Engineering, Universidad Rey Juan Carlos, Spain

 Covering diverse subjects such as rendering techniques, graphic processors, and physicsbased simulation, as well as videogames and virtual reality.

Sep. 2010 – Bachelor's Degree in Multimedia Engineering
Sep. 2015

Higher School of Engineering University do M

Higher School of Engineering, Universitat de València, Spain

 Combines audiovisual communication with computer engineering, especially deepening in multimedia systems and all related areas (graphics, simulation, sound, ...).





PUBLICATIONS

Aug. 2021 Soft-Tissue Simulation for Computational Planning of Orthognathic Surgery

P. Alcañiz, J. Pérez, A. Gutiérrez, H. Barreiro, Á. Villalobos, D. Miraut, C. Illana, MA. Otaduy

Journal of Personalized Medicine

Jul. 2021 Natural Tactile Interaction with Virtual Clay

H. Barreiro, J. Torres, MA. Otaduy

Proc. of World Haptics Conference, 2021

Jul. 2020 Robust Eulerian-on-Lagrangian Rods

R.M. Sánchez-Banderas, A. Rodríguez, H. Barreiro, MA. Otaduy

ACM Trans. on Graphics (Proc. of ACM SIGGRAPH), Volume 39, Number 4 - 2020

Feb. 2020 Path Routing Optimization for STM Ultrasound Rendering

H. Barreiro, S. Sinclair, MA. Otaduy

IEEE Trans Haptics. 2020 Feb 24. doi: 10.1109/TOH.2019.2963647.

Jul. 2019 Ultrasound Rendering of Tactile Interaction with Fluids

H. Barreiro, S. Sinclair, MA. Otaduy

2019 IEEE World Haptics Conference (WHC). IEEE, 2019

Nov. 2017 Conformation Constraints for Efficient Viscoelastic Fluid Simulation

H. Barreiro, I. García-Fernández, I. Alduán, MA. Otaduy

ACM Trans. on Graphics (Proc. of ACM SIGGRAPH Asia), 2017

Jul. 2015 Real-time Inextensible Hair with Volume and Shape

R. M. Sánchez-Banderas, H. Barreiro, I. García-Fernández, M. Pérez Martínez

Congreso Español de Informática Gráfica, 2015















AWARDS PA

Best Doctoral Thesis Award

Congreso Español de Informática Gráfica (CEIG), Eurographics Spanish Section

PATENTS

System and method for representing the tactile interaction employed by an array of ultrasound transducers

H. Barreiro, S. Sinclair, MA. Otaduy

U.S. Patent Application No. 17/904,042

CERTIFICATIONS

Machine Learning

Stanford Online @ Coursera

Neural Networks and Deep Learning Deeplearning.ai @ Coursera

Improving Deep Neural Networks: Hyperparameter tuning Deeplearning.ai @ Coursera

PROFESSIONAL INTERESTS



Mechanical simulation

Machine

learning



Real-time

Mixed reality (AR & VR)



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Haptic rendering

OTHER SKILLS AND PERSONAL INTERESTS

ToolsVisual Studio, VS CodeFrameworksEigen, PyTorch, Numpy, SympyHPCCUDA, OpenCL, OpenGL, GLSL, HLSL

Game Engines Unity, Godot

Hobbies & Interests Single player videogames, travelling, trying out

new food, comedy shows, petting dogs, naps

For further information, please contact me or visit my online portfolio.

Thank you for your time